
MCBSP LLD

Release Notes

Applies to Product Release: 01.00.00.02:
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MCBSP LLD version 01.00.00.02

Overview

This document provides the release information for the latest MCBSP Low Level Driver which should be used by drivers and application that interface with MCBSP IP.

MCBSP LLD module includes:

- Pre-compiled library for DSP (Big and Little) Endian of MCBSP LLD
- Source code
- API reference guide
- Design Documentation

LLD Dependencies

LLD is dependent on following external components delivered in CSL/LLDs package:

- CSL
- EDMA3 LLD

New/Updated Features and Quality

This is an **engineering release**, tested by the development team.

Release 1.0.0.2

- Added support for ping pong mechanism using initially submitted frames.
- Bug fixes

Release 1.0.0.1

- Bug fixes (See IR section below)

Release 1.0.0.0

- Initial release of MCBSP low level driver

Resolved Incident Reports (IR)

Table 1 provides information on IR resolutions incorporated into this release.

Table 1 Resolved IRs for this Release

IR Parent/ Child Number	Severity Level	IR Description

Known Issues/Limitations

IR Parent/ Child Number	Severity Level	IR Description

Licensing

Please refer to the software Manifest document for the details.

Delivery Package

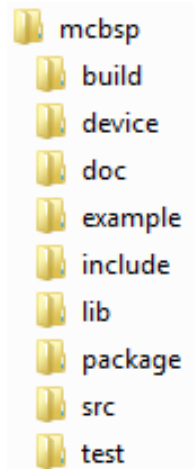
There is no separate delivery package. The MCBSP LLD is being delivered as part of CSL/LLDs package.

Installation Instructions

The LLD is currently bundled as part of CSL/LLDs package. Refer installation instruction to the release notes provided for CSL/LLDs.

Directory Structure

The following is the directory structure after the MCBSP LLD package has been installed:



The following table explains each individual directory:

Directory Name	Description
ti/drv/mcbasp	The top level directory contains the following:- <ol style="list-style-type: none"> <u>Environment configuration batch file</u> The file “setupenv.bat” is used to configure the build environment for the MCBSP low level driver. <u>XDC Build and Package files</u> These files (config.bld, package.xdc etc) are the XDC build files which are used to create the MCBSP package. <u>Exported Driver header file</u> Header files which are provided by the MCBSP low level driver and should be used by the application developers for driver customization and usage.
ti/drv/mcbasp/build	The directory contains internal XDC build related files which are used to create the MCBSP low level driver package.
ti/drv/mcbasp/device	The directory contains the device specific files for the MCBSP low level driver.
ti/drv/mcbasp/docs	The directory contains the MCBSP low level driver documentation.
ti/drv/mcbasp/example	The “example” directory in the MCBSP low level driver has the Digital Loopback example.
ti/drv/mcbasp/include	The “include” directory has private MCBSP low level driver header files. These files should not be used by application developers.
ti/drv/mcbasp/lib	The “lib” folder has pre-built Big and Little Endian libraries for the MCBSP low level driver along with their <u>code/data size information</u> .
ti/drv/mcbasp/package	Internal MCBSP low level driver package files.
ti/drv/mcbasp/src	Source code for the MCBSP low level driver.

Example Sample Application

The section documents information about the example code located in the MCBSP LLD package.

MCBSP Digital Loopback Example

This sample application demonstrates the use of the MCBSP driver in digital loopback mode. The MCBSP driver supports only DMA mode of operation. The MCBSP sample application has a project, called `MCBSP_DigLpbkExampleProject`.

This project (sample application) is used to configure the MCBSP in loopback mode and configures the required clocks, etc. The driver along with the required component modules are configured in `mcbSPMasterDigLpbk.cfg` file. The required memory for the heap is also created here. The `mcbSPMasterDigLpbk.cfg` file contains the remaining BIOS configuration like the configuration of the event combiner etc. This helps to map the MCBSP events to the CPU interrupts.

The `mcbSPStartDigLpbkApp` function running in `mcbSPDigLpbkAppTask` exercises the MCBSP driver. The application uses MCBSP internal clock to drive frame sync and data bit clocks. The example application opens 2 channels (one RX and one TX) for the data transfer. A source buffer filled with known pattern is transferred from CPU memory to MCBSP peripheral (to DX pin - TX path) with the help of EDMA controller. The digital loopback mode in MCBSP loops this data back to the DR pin (RX path) and EDMA controller receives this data and stores in the destination buffer in CPU memory. The sample application sends and receives configured number of data bytes for multiple iterations and each time verifies the data integrity by comparing the transmitted and received data buffers.

Customer Documentation List

Table 2 lists the documents that are accessible through the `/docs` folder on the product installation CD or in the delivery package.

Table 2 Product Documentation included with this Release

Document #	Document Title	File Name
1	API documentation (generated by Doxygen)	docs/mcbSPllDDocs.chm
2	Design Document	docs/MCBSP_LLD_SDS.pdf
3	Software Manifest	docs/MCBSP_LLD_SoftwareManifest.pdf