

## **PROGRAM EVM IMAGES**

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# **Users Guide**

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Ver 2.3

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# BIOS MCSDK RECOVERING FACTORY DEFAULT IMAGES

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## 1 Overview

This release provides the images for the factory to program on the eeprom, nand and nor for EVM6670L, EVM6678L, EVM6657L, EVM6618L and EVMK2H.

Comment [a1]:

## 2 Revision History

Revision	Details
1.0	Initial Version
1.1	Rearranged the sections
1.2	Updating the Linux instructions.
1.3	Added C6670 EVM support
1.4	Updated scripts and binaries
1.7	Updated to CCS 5.1
1.8	Fixed POST and NOR instructions
1.9	Added C6657 EVM support
2.0	Added EVMK2H support

## 3 Files Provided

### 3.1 C6678 EVM Files

The following files are the factory default images under program\_evm\binaries\evm6678l.

Note: Please note that nand.bin and nand\_oob.bin are not supplied from BIOS MCSDK releases. Please refer to the DVD shipped along with the EVM for nand.bin file.

File Name	Description
eeprom50.bin	Binary file Power On Self Test (POST)
eeprom51.bin	Binary file for IBL
eepromwriter_evm6678l.out	eeprom Writer DSP executable
eepromwriter_input.txt	eeprom writer input for execution
eepromwriter_input50.txt	eeprom writer input for writing images to 0x50
eepromwriter_input51.txt	eeprom writer input for writing images to 0x51
nandwriter_evm6678l.out	Nand Writer DSP executable
nand_writer_input.txt	nand image writer input file
nor.bin	Binary file for the NOR image having HUA demo
norwriter_evm6678l.out	NOR image writer DSP executable
nor_writer_input.txt	NOR image writer input file

### 3.2 C6670 and TCI6618 EVM Files

C6670 EVM and TCI6618 EVM use the same factory default images under program\_evm\binaries\evm6670l.

File Name	Description
eeprom50.bin	Binary file Power On Self Test (POST)
eeprom51.bin	Binary file for IBL
eepromwriter_evm6670l.out	eeprom Writer DSP executable
eepromwriter_input.txt	eeprom writer input for execution
eepromwriter_input50.txt	eeprom writer input for writing images to 0x50
eepromwriter_input51.txt	eeprom writer input for writing images to 0x51
nandwriter_evm6670l.out	Nand Writer DSP executable
nand_writer_input.txt	nand image writer input file
nor.bin	Binary file for the NOR image having HUA demo
norwriter_evm6670l.out	NOR image writer DSP executable
nor_writer_input.txt	NOR image writer input file

### 3.3 C6657 EVM Files

C6657 EVM use the same factory default images under program\_evm\binaries\evm6657l.

Revision A:

File Name	Description
eeprom50.bin	Binary file Power On Self Test (POST)
eeprom51.bin	Binary file for IBL
eepromwriter_evm6657l.out	eeprom Writer DSP executable
eepromwriter_input.txt	eeprom writer input for execution
eepromwriter_input50.txt	eeprom writer input for writing images to 0x50
eepromwriter_input51.txt	eeprom writer input for writing images to 0x51
nandwriter_evm6670l.out	Nand Writer DSP executable
nand_writer_input.txt	nand image writer input file
nor.bin	Binary file for the NOR image having HUA demo
norwriter_evm6657l.out	NOR image writer DSP executable
nor_writer_input.txt	NOR image writer input file

### 3.4 EVMK2H Files

EVMK2H uses the factory default images under program\_evm\binaries\evmk2h.

File Name	Description
nand.bin	Nand UBIFS image (keystone-evm-ubifs.ubi)
nandwriter_evmk2h.out	Nand Writer DSP executable
nand_writer_input.txt	nand image writer input file
	SPI NOR file for U-Boot
nor.bin	(u-boot-spi-keystone-evm.gph)
norwriter_evmk2h.out	NOR image writer DSP executable
nor_writer_input.txt	NOR image writer input file

## 4 MD5SUM utility used

Please use the md5sum utility from the below link  
<http://www.pc-tools.net/files/win32/freeware/md5sums-1.2.zip>

## 5 Device Support

- The images provided support EVM6678L, EVM6657L, EVM6670L, EVM6618L and EVMK2H in Little Endian Mode.

## 6 Directory Structure

The program\_evm (top-level) directory is intended to hold the \*DSS\* script for the Code Composer Studio which programs the default images to NAND/NOR/EEPROM.

The binaries/evmxxxx directory is intended to hold all the factory default images and the respective writers.

The configs/evmxxxx directory is intended to hold the “CCS target configuration files”. Four pre-configured configurations are provided for each EVM type except evm6657l and evmk2h: one for inbuilt XDS100 in Windows, one for XDS560 mezzanine card in Windows, one for inbuilt XDS100 in Linux, and one for XDS560 mezzanine card in Linux. For evm6657l, besides the mentioned configuration files, another for XDS200 card in Windows is provided. For evmk2h, one configuration file is present for Windows, and one is present for linux.

The gel directory holds custom GEL files for the boards present. It also contains a README.txt for the gel files’ usage.

The logs directory is empty and will be used to store logs. Logs are automatically generated when using program\_evm.js to flash evmxxxx devices.

```

program_evm
program_evm_userguide.pdf
program_evm.js

binaries
└── evm6678l
    eeprom50.bin
    eeprom51.bin
    eepromwriter_evm6678l.out
    eepromwriter_input.txt
    eepromwriter_input50.txt
    eepromwriter_input51.txt
    nand.bin
    nandwriter_evm6678l.out
    nand_writer_input.txt
    nor.bin
    norwriter_evm6678l.out
    nor_writer_input.txt
└── evm6670l
    eeprom50.bin
    eeprom51.bin
    eepromwriter_evm6670l.out
    eepromwriter_input.txt
    eepromwriter_input50.txt
    eepromwriter_input51.txt
    nand.bin
    nandwriter_evm6670l.out

```

*Revision A:*

---

```
nand_writer_input.txt  
nor.bin  
norwriter_evm6670l.out  
nor_writer_input.txt  
└── evm6657l  
    eeprom50.bin  
    eeprom51.bin  
    eepromwriter_evm6657l.out  
    eepromwriter_input.txt  
    eepromwriter_input50.txt  
    eepromwriter_input51.txt  
    nand.bin  
    nandwriter_evm6657l.out  
    nand_writer_input.txt  
    nor.bin  
    norwriter_evm6657l.out  
    nor_writer_input.txt  
    └── evmk2h  
        eepromwriter_evmk2h.out  
        eepromwriter_input.txt  
        eepromwriter_input50.txt  
        eepromwriter_input51.txt  
        nand.bin  
        nandwriter_evmk2h.out  
        nand_writer_input.txt  
        nor.bin  
        norwriter_evmk2h.out  
        nor_writer_input.txt  
configs  
└── evm6678l  
    evm6678l.ccxml  
    evm6678le.ccxml  
    evm6678l-linuxhost.ccxml  
    evm6678le-linuxhost.ccxml  
└── evm6670l  
    evm6670l.ccxml  
    evm6670le.ccxml  
    evm6670l-linuxhost.ccxml  
    evm6670le-linuxhost.ccxml  
└── evm6657l  
    evm6657l.ccxml  
    evm6657le.ccxml  
    evm6657ls.ccxml  
    evm6657l-linuxhost.ccxml  
    evm6657le-linuxhost.ccxml  
└── evmk2h
```

```

evmk2h.ccxml
evmk2h-linuxhost.ccxml
gel
  evmc6670l.gel
  evmc6678l.gel
  evmc6657l.gel
  evmtci6638k2k.gel
  README.txt
logs (empty directory)

```

## 7 Programming the bin files

This section assumes you have installed BIOS-MCSDK (MCSDK 3.x for EVMK2H) and Code Composer Studio.

### 7.1 Set the EVM Dip switches

#### 7.2.47.1.1 For all the EVM 6670 and EVM6678

Make sure the EVM dip switches are kept as below.

SWITCH	Pin1	Pin2	Pin3	Pin4
SW3	Off	On	On	On
SW4	On	On	On	On
SW5	On	On	On	On
SW6	On	On	On	On

#### 7.2.37.1.2 For EVM6657

Make sure the EVM dip switches are kept as below.

SWITCH	Pin1	Pin2	Pin3	Pin4	Pin5	Pin6	Pin7	Pin8
SW3	Off	On						
SW5	On							

#### 7.2.57.1.3 For EVMK2H

Make sure the EVM dip switches are kept as below.

SWITCH	Pin1	Pin2	Pin3	Pin4
SW1	Off	Off	Off	On

### **7.3.27.2 Set the Environment Variables**

Please make sure the below environment variables needs to be set. Otherwise there could be some unexpected behavior experienced.

#### **7.3.27.2.1 Windows**

1. Set the **DSS\_SCRIPT\_DIR** environment variable (Mandatory) to Code Composer Studio scripting bin directory.

Example:

```
set DSS_SCRIPT_DIR="C:\ti\ccsv5\ccs_base\scripting\bin"
```

2. Set the **PROGRAM\_EVM\_TARGET\_CONFIG\_FILE** environment variable:  
xds100, xds 560 mezzanine, xds 200 and xds 2xx are supported. If you don't want to use the default target configuration file, you can set the path here.

Example:

```
set PROGRAM_EVM_TARGET_CONFIG_FILE=C:\Documents and Settings\  
\user\CCSTargetConfigurations\myC667xl.ccxml
```

NOTE: Please note that

- [1] The **DSS\_SCRIPT\_DIR** env variable needs the opening/closing quotes,
- [2] The **PROGRAM\_EVM\_TARGET\_CONFIG\_FILE** variable, on the other hand, \*should not\* have the quotes around it if the path has spaces in it.

If **PROGRAM\_EVM\_TARGET\_CONFIG\_FILE** environment variable is not set, the DSS script will use the default ccxml files that support the following emulators for CCS 5.1.0:

1. xds100 inbuilt (evm667xl.ccxml)
2. xds560 mezzanine card (evm667xle.ccxml)
3. xds2xx mezzanine card (evmk2h.ccxml)

Please note that depending on the emulator selected the restore image time may vary. For example, if xds100 inbuilt emulator is selected, the entire process may take over 60 minutes. If xds560 mezzanine card emulator is selected, the process may take about 10 minutes.

#### **7.3.27.2.2 Linux**

1. Set the **DSS\_SCRIPT\_DIR** environment variable (Mandatory) to your Code Composer Studio scripting bin directory.

Example:

```
export DSS_SCRIPT_DIR=~/ti/ccsv5/ccs_base/scripting/bin
```

2. Set the **PROGRAM\_EVM\_TARGET\_CONFIG\_FILE** environment variable

Please provide the path for the ccxml file that is created for the EVM for the CCS. Please note that this step can be skipped for CCS 5.1.0 users since the program evm has a default target configuration files bundled for xds100 and xds560 mezzanine cards.

Example:

```
export PROGRAM_EVM_TARGET_CONFIG_FILE =configs/evm667xl/my_evm667xl.ccxml
```

If *PROGRAM\_EVM\_TARGET\_CONFIG\_FILE* environment variable is not set, the DSS script will use the default ccxml files that support the following emulators for CCS 5.1.0:

1. xds100 inbuilt (evm667xl.ccxml)
2. xds560 mezzanine card (evm667xle.ccxml)
3. xds2xx mezzanine card (evmk2h.ccxml)

Please note that depending on the emulator selected the restore image time may vary. For example, if xds100 inbuilt emulator is selected, the entire process may take over 60 minutes. If xds560 mezzanine card emulator is selected, the process may take about 10 minutes.

#### **7.47.3 Copy the custom GEL files**

Please refer to the README.txt in the program\_evm\gel directory.

#### **7.57.4 Run DDR3 GEL Scripts (EVMK2H only)**

This issue has been fixed in the KeystoneII EMUPACK v1.0.0.3. If using a previous version, please update to the new version or follow these instructions:

#### **7.67.5 Some versions of the KeystoneII EMUPACK do not contain an OnTargetConnect() function. With these versions, it is necessary to connect to the EVM through CCS and run any of the DDR3A and DDR3B init hotmenu functions before running program\_evm. After the functions are run, disconnect from the EVM (do not power cycle the evm).DSS Script Arguments**

##### **7.6.47.5.1 General Script Usage**

Script Usage:

```
[MCSDK]\tools\program_evm>%DSS_SCRIPT_DIR%\dss.bat program_evm.js  
[tmidx|tmds]evm(6678|6670|6618|6657|k2h) [l|le|ls] [-le|-be]
```

**MCSDK:** refers to the MCSDK installation directory, eg. C:\Program Files\Texas Instruments\mcSDK\_2\_00\_06\_18\

**Note:** For EVMK2H do not use [tmidx|tmds] or [l|le|ls].

**tmidx (optional):** TMDX type EVM

**tmds (optional):** TMDS type EVM

**6678:** C6678 device

**6670:** C6670 device

*Revision A:*

---

**6618:** TCI6618 device

**6657:** C6657 device

k2h :TCI6638 device

**I:** Low cost EVM

**le:** EVM uses 560 Mezzanine Emulator daughter card

**ls:** EVM uses XDS200 Emulator card

**-le (optional):** Little Endian (default)

**-be (optional):** Big Endian

#### 7.6.27.5.2 Formatting the NAND Flash

The program\_evm supports formatting the NAND device as below.

```
[MCSDK]\tools\program_evm>%DSS_SCRIPT_DIR%\dss.bat program_evm.js  
tmdxevm66571 format-nand
```

Warning: Please note that this would erase all the nand blocks.

#### 7.7.6 Executing the DSS script to restore factory default images.

##### 7.7.47.6.1 Windows

1. cd “\program\_evm” directory
2. Set the necessary environment variables as described in section 7.2.1.
3. Using the DSS Script batch file, run the “program\_evm.js” script command from program\_evm directory.

**Example:**

```
\program_evm>%DSS_SCRIPT_DIR%\dss.bat program_evm.js TMDXEVN6678L-le
```

This will write all the little endian images to C6678 low cost EVM using XDS 100 emulator.

```
\program_evm>%DSS_SCRIPT_DIR%\dss.bat program_evm.js TMDXEVN6670Le-le
```

This will write all the little endian images to C6670 low cost EVM using XDS 560 Mezzanine emulator.

```
\program_evm>%DSS_SCRIPT_DIR%\dss.bat program_evm.js evmk2h-le
```

This will write all the little endian images to K2H EVM.

#### **7.7.27.6.2 Linux**

1. cd “program\_evm” directory
2. Set the necessary environment variables as described under section 7.2.2.
3. Using the DSS Script batch file, run the “program\_evm.js” script command from program\_evm directory.

#### **Example:**

```
/program_evm>$DSS_SCRIPT_DIR/dss.sh program_evm.js TMDXEV6678L-le  
This will write all the little endian images to C6678 low cost EVM using XDS  
100 emulator.
```

```
/program_evm>$DSS_SCRIPT_DIR/dss.sh program_evm.js TMDXEV6670Le-le  
This will write all the little endian images to C6670 low cost EVM using XDS  
560 Mezzanine emulator.
```

```
/program_evm>$DSS_SCRIPT_DIR/dss.sh program_evm.js evmk2h-le  
This will write all the little endian images to K2H EVM.
```

#### **7.7.37.6.3 Sample DSS Script output for Windows and Linux**

The sample output after running the DSS Script is as below.

**Please Note: the loading of nand.bin can take up to a few minutes depending on the image size.**

```
board: evm6657l  
Endian: Little  
Emulation: XDS200 emulator  
Binaries: C:\Program Files\Texas  
Instruments\mcSDK_2_01_00_03\tools\program_evm/binaries\evm6657l/  
Ccxml: C:\Documents and  
Settings\xxxxxxx\user\CCSTargetConfigurations\evmc6657.ccxml  
C66xx_0: GEL Output:  
Connecting Target...  
  
C66xx_0: GEL Output: DSP core #0
```

*Revision A:*

---

*C66xx\_0: GEL Output: C6657L GEL file Ver is 1.0*

*C66xx\_0: GEL Output: Global Default Setup...*

*C66xx\_0: GEL Output: Setup Cache...*

*C66xx\_0: GEL Output: L1P = 32K*

*C66xx\_0: GEL Output: L1D = 32K*

*C66xx\_0: GEL Output: L2 = ALL SRAM*

*C66xx\_0: GEL Output: Setup Cache... Done.*

*C66xx\_0: GEL Output: Main PLL (PLL1) Setup ...*

*C66xx\_0: GEL Output: PLL1 Setup for DSP @ 1000.0 MHz.*

*C66xx\_0: GEL Output: SYSCLK2 = 333.3333 MHz, SYSCLK5 = 200.0 MHz.*

*C66xx\_0: GEL Output: SYSCLK8 = 15.625 MHz.*

*C66xx\_0: GEL Output: PLL1 Setup... Done.*

*C66xx\_0: GEL Output: Power on all PSC modules and DSP domains...*

*C66xx\_0: GEL Output: Power on all PSC modules and DSP domains... Done.*

*C66xx\_0: GEL Output: DDR3 PLL (PLL2) Setup ...*

*C66xx\_0: GEL Output: DDR3 PLL Setup... Done.*

*C66xx\_0: GEL Output: DDR3 Init begin (1333 auto)*

*C66xx\_0: GEL Output: XMC Setup ... Done*

*C66xx\_0: GEL Output:*

*DDR3 initialization is complete.*

*C66xx\_0: GEL Output: DDR3 Init done*

*C66xx\_0: GEL Output: DDR3 memory test... Started*

*C66xx\_0: GEL Output: DDR3 memory test... Passed*

*C66xx\_0: GEL Output: PLL and DDR3 Initialization completed(0) ...*

*C66xx\_0: GEL Output: configSGMIIserdes Setup... Begin*

*C66xx\_0: GEL Output: SGMII SERDES has been configured.*

*C66xx\_0: GEL Output: Enabling EDC ...*

*C66xx\_0: GEL Output: L1P error detection logic is enabled.*

*C66xx\_0: GEL Output: L2 error detection/correction logic is enabled.*

*C66xx\_0: GEL Output: MSMC error detection/correction logic is enabled.*

*C66xx\_0: GEL Output: Enabling EDC ...Done*

*C66xx\_0: GEL Output: Global Default Setup... Done.*

*Revision A:*

*Start writing eeprom50*

*Writer:C:\Program Files\Texas*

*Instruments\mcSDK\_2\_01\_00\_03\tools\program\_evm/binaries\evm6657l\EEPROMwriter\_ev  
m6657l.out*

*Image:C:\Program Files\Texas*

*Instruments\mcSDK\_2\_01\_00\_03\tools\program\_evm/binaries\evm6657l\EEPROM50.bin*

*C66xx\_0: GEL Output: Invalidate All Cache...*

*C66xx\_0: GEL Output: Invalidate All Cache... Done.*

*C66xx\_0: GEL Output: GEL Reset...*

*C66xx\_0: GEL Output: GEL Reset... Done.*

*C66xx\_0: GEL Output: Disable all EDMA3 interrupts and events.*

*EEPROM Writer Utility Version 01.00.00.05*

*Writing 59128 bytes from DSP memory address 0x0c000000 to EEPROM bus address  
0x0050 starting from device address 0x0000 ...*

*Reading 59128 bytes from EEPROM bus address 0x0050 to DSP memory address  
0x0c010000 starting from device address 0x0000 ...*

*Verifying data read ...*

*EEPROM programming completed successfully*

*Start writing eeprom51*

*Writer:C:\Program Files\Texas*

*Instruments\mcSDK\_2\_01\_00\_03\tools\program\_evm/binaries\evm6657l\EEPROMwriter\_ev  
m6657l.out*

*Image:C:\Program Files\Texas*

*Instruments\mcSDK\_2\_01\_00\_03\tools\program\_evm/binaries\evm6657l\EEPROM51.bin*

*C66xx\_0: GEL Output: Invalidate All Cache...*

*C66xx\_0: GEL Output: Invalidate All Cache... Done.*

*C66xx\_0: GEL Output: GEL Reset...*

*C66xx\_0: GEL Output: GEL Reset... Done.*

*C66xx\_0: GEL Output: Disable all EDMA3 interrupts and events.*

*EEPROM Writer Utility Version 01.00.00.05*

*Writing 47848 bytes from DSP memory address 0x0c000000 to EEPROM bus address 0x0051 starting from device address 0x0000 ...*

*Reading 47848 bytes from EEPROM bus address 0x0051 to DSP memory address 0x0c010000 starting from device address 0x0000 ...*

*Verifying data read ...*

*EEPROM programming completed successfully*

*Writer:C:\Program Files\Texas Instruments\mcsdk\_2\_01\_00\_03\tools\program\_evm/binaries/evm6657l/nandwriter\_evm657l.out*

*NAND:C:\Program Files\Texas Instruments\mcsdk\_2\_01\_00\_03\tools\program\_evm/binaries/evm6657l/nand.bin*

*Required NAND files does not exist in C:\Program Files\Texas Instruments\mcsdk\_2\_01\_00\_03\tools\program\_evm/binaries/evm6657l/*

*Writer:C:\Program Files\Texas Instruments\mcsdk\_2\_01\_00\_03\tools\program\_evm/binaries/evm6657l/norwriter\_evm6657l.out*

*NOR:C:\Program Files\Texas Instruments\mcsdk\_2\_01\_00\_03\tools\program\_evm/binaries/evm6657l/nor.bin*

*C66xx\_0: GEL Output: Invalidate All Cache...*

---

*Revision A:*

---

*C66xx\_0: GEL Output: Invalidate All Cache... Done.*

*C66xx\_0: GEL Output: GEL Reset...*

*C66xx\_0: GEL Output: GEL Reset... Done.*

*C66xx\_0: GEL Output: Disable all EDMA3 interrupts and events.*

*Start loading nor.bin*

*Start programming NOR*

*2012\_08\_23\_165121*

*NOR Writer Utility Version 01.00.00.03*

*Flashing sector 0 (0 bytes of 664115)*

*Flashing sector 1 (65536 bytes of 664115)*

*Flashing sector 2 (131072 bytes of 664115)*

*Flashing sector 3 (196608 bytes of 664115)*

*Flashing sector 4 (262144 bytes of 664115)*

*Flashing sector 5 (327680 bytes of 664115)*

*Flashing sector 6 (393216 bytes of 664115)*

*Flashing sector 7 (458752 bytes of 664115)*

*Flashing sector 8 (524288 bytes of 664115)*

*Flashing sector 9 (589824 bytes of 664115)*

*Flashing sector 10 (655360 bytes of 664115)*

*Reading and verifying sector 0 (0 bytes of 664115)*

*Reading and verifying sector 1 (65536 bytes of 664115)*

*Reading and verifying sector 2 (131072 bytes of 664115)*

*Reading and verifying sector 3 (196608 bytes of 664115)*

*Reading and verifying sector 4 (262144 bytes of 664115)*

*Reading and verifying sector 5 (327680 bytes of 664115)*

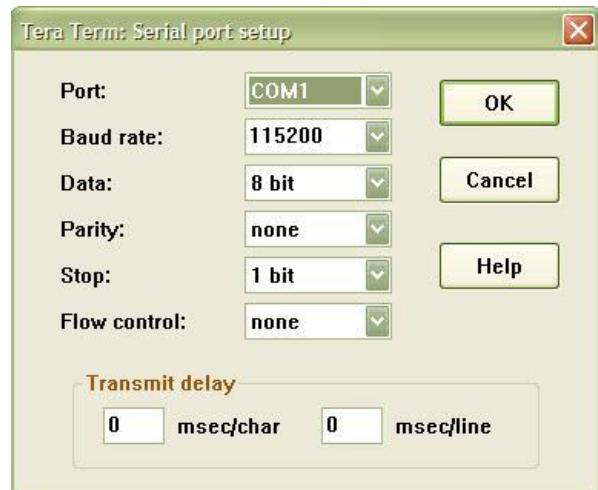
*Reading and verifying sector 6 (393216 bytes of 664115)*

*Reading and verifying sector 7 (458752 bytes of 664115)  
 Reading and verifying sector 8 (524288 bytes of 664115)  
 Reading and verifying sector 9 (589824 bytes of 664115)  
 Reading and verifying sector 10 (655360 bytes of 664115)  
 NOR programming completed successfully  
 End programming NOR*

## 48 Verification

### 4.18.1 Serial Port Setup

Connect the RS232 Serial cable provided in the box to the serial port of the Host PC. If Host is running Windows OS, start tera term and configure the serial port settings as follows.



### 4.28.2 Verifying POST

- Set the dip switches as below for EVM6670 and EVM6678.

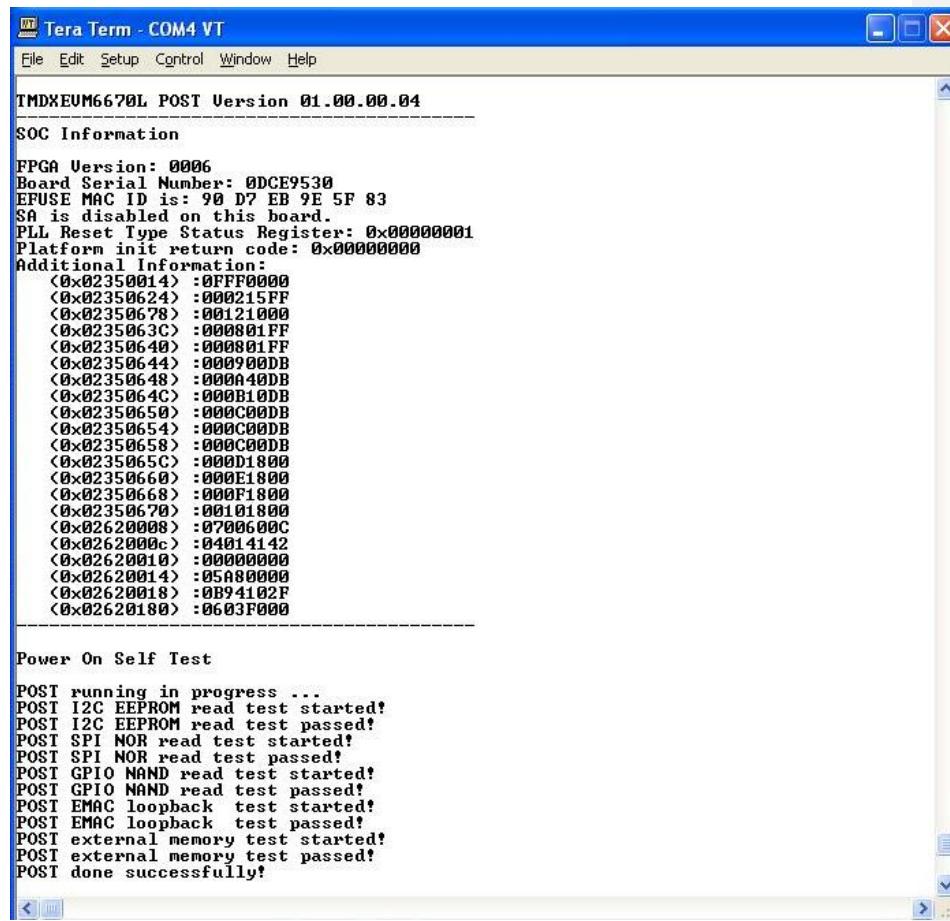
SWITCH	Pin1	Pin2	Pin3	Pin4
SW3	Off	Off	On	Off
SW4	On	On	On	On
SW5	On	On	On	On
SW6	On	On	On	On

*Revision A:*

For EVM6657, set the dip switches as below.

SWITCH	Pin1	Pin2	Pin3	Pin4	Pin5	Pin6	Pin7	Pin8
SW3	Off	Off	On	Off	On	On	On	On
SW5	On							

2. Power Cycle the board, wait for the PC to recognize the EVM card, then hit Rst\_FULL button on the EVM.
3. Wait for the “POST done successfully!” message.
4. The Screen Shot on the UART should be as below.



The screenshot shows the Tera Term window titled "Tera Term - COM4 VT". The title bar includes standard menu options: File, Edit, Setup, Control, Window, Help. Below the title bar, the text "TMDXEUM6670L POST Version 01.00.00.04" is displayed. The main content area is divided into two sections: "SOC Information" and "Power On Self Test".

**SOC Information**

```
FPGA Version: 0006
Board Serial Number: 0DCE9530
EFUSE MAC ID is: 90 D7 EB 9E 5F 83
SA is disabled on this board.
PLL Reset Type Status Register: 0x00000001
Platform init return code: 0x00000000
Additional Information:
<0x02350014> :0FFF0000
<0x02350624> :000215FF
<0x02350678> :00121000
<0x0235063C> :000801FF
<0x02350640> :000801FF
<0x02350644> :000900DB
<0x02350648> :000A40DB
<0x0235064C> :000B10DB
<0x02350650> :000C00DB
<0x02350654> :000C00DB
<0x02350658> :000C00DB
<0x0235065C> :000D1800
<0x02350660> :000E1800
<0x02350668> :000F1800
<0x02350670> :00101800
<0x02620008> :0700600C
<0x02620000> :04814142
<0x02620010> :00000000
<0x02620014> :05A80000
<0x02620018> :0894102F
<0x02620180> :0603F000
```

**Power On Self Test**

```
POST running in progress ...
POST I2C EEPROM read test started!
POST I2C EEPROM read test passed!
POST SPI NOR read test started!
POST SPI NOR read test passed!
POST GPIO NAND read test started!
POST GPIO NAND read test passed!
POST EMAC loopback test started!
POST EMAC loopback test passed!
POST external memory test started!
POST external memory test passed!
POST done successfully!
```

**4.2.18.2.1 Entering Serial Number to the EVM**

1. After POST completes all the tests successfully, user can key in "ti" (small caps) to enter the board serial number.
2. Once the 10 digits serial number is entered successfully, power cycle the board to verify the new serial number.

**7.88.3 Verifying NOR****7.8.18.3.1 EVMC6670, EVMC6678 and EVMC6657**

1. Set the dip switches as below for EVM6670 and EVM6678.

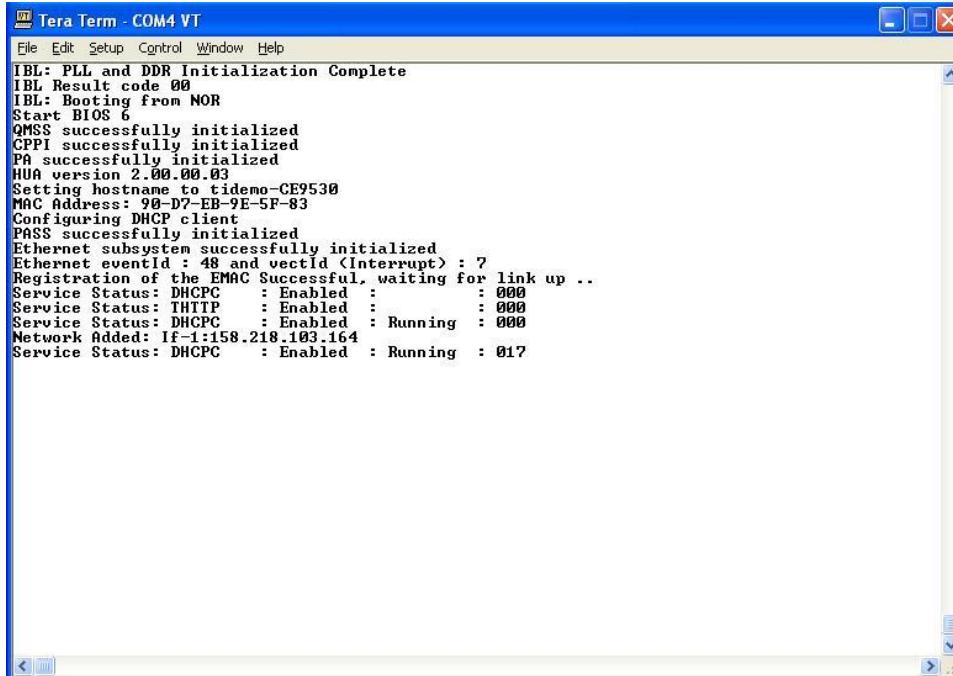
<b>SWITCH</b>	<b>Pin1</b>	<b>Pin2</b>	<b>Pin3</b>	<b>Pin4</b>
SW3	Off	Off	On	Off
SW4	On	On	On	On
SW5	On	On	On	<b>Off</b>
SW6	On	On	On	On

For EVM6657, set the dip switches as below.

<b>SWITCH</b>	<b>Pin1</b>	<b>Pin2</b>	<b>Pin3</b>	<b>Pin4</b>	<b>Pin5</b>	<b>Pin6</b>	<b>Pin7</b>	<b>Pin8</b>
SW3	<b>Off</b>	Off	On	Off	On	On	On	On
SW5	On	On	On	Off	On	On	On	On

2. Power Cycle the board, wait for the PC to recognize the EVM card, then hit Rst\_FULL button on the EVM.
3. Make sure the evm is connected to the DHCP server.
4. The HUA boot log will show up on the UART. A sample screen for EVM6678 is shown below.

*Revision A:*



The screenshot shows a window titled "Tera Term - COM4 VT". The menu bar includes File, Edit, Setup, Control, Window, and Help. The main window displays the following U-Boot initialization log:

```
IBL: PLL and DDR Initialization Complete
IBL Result code 00
IBL: Booting from NOR
Start BIOS 6
QMSI successfully initialized
CPPI successfully initialized
PA successfully initialized
HUA version 2.00.00.03
Setting hostname to tidemo-CE9530
MAC Address: 90-D7-EB-9E-5F-83
Configuring DHCP client
PASS successfully initialized
Ethernet subsystem successfully initialized
Ethernet eventid : 48 and vectid <Interrupt> : ?
Registration of the EMAC Successful, waiting for link up ..
Service Status: DHCPC : Enabled : 000
Service Status: THTTP : Enabled : 000
Service Status: DHCPC : Enabled : Running : 000
Network Added: If-1:158.218.103.164
Service Status: DHCPC : Enabled : Running : 017
```

#### 7.8.28.3.2 EVMK2H

1. Set the dip switches as below.

SWITCH	Pin1	Pin2	Pin3	Pin4
SW1	Off	Off	On	Off

2. Power Cycle the board.
3. Make sure the evm is connected to the DHCP server.
4. U-Boot will show up on the UART. A sample screen is shown below.

```

Tera Term Web 3.1 - COM1 VT
File Edit Setup Control Window Help
U-Boot SPL 2013.01-g715e3ec-dirty (Feb 27 2013 - 11:24:10)
SF: Detected N25Q128A with page size 64 KiB, total 16 MiB

U-Boot 2013.01-g715e3ec-dirty (Feb 27 2013 - 11:24:10)

I2C: ready
DRAM: 1 GiB
WARNING: Caches not enabled
NAND: 128 MiB
Net: Ethernet PHY: 88E1111 @ 0x00
TCI6614-EMAC
Warning: failed to set MAC address

Hit any key to stop autoboot: 0
TCI6638 EVM #
TCI6638 EVM #

```

#### 7.98.4 Verifying NAND

##### 7.9.18.4.1 EVMC6670, EVMC6678 and EVMC6657

- Set the dip switches as below for EVM 6670 and EVM6678.

SWITCH	Pin1	Pin2	Pin3	Pin4
SW3	Off	Off	On	Off
SW4	On	<b>Off</b>	On	On
SW5	On	On	On	Off
SW6	On	On	On	On

Note there is no NAND.bin provided for C6657 as there is no Linux support on C6657.  
Please refer to device hardware setup documentation for booting from NAND.

- Power Cycle the board, wait for the PC to recognize the EVM card, then hit Rst\_FULL button on the EVM.
- Wait for a minute
- The Linux boot log will show up on the UART. A sample screen for EVM6678 is shown below.

```

IBL: PLL and DDR Initialization Complete
IBL Result code 00
IBL: Booting from NAND
Linux version 2.6.34-evmc6670.el-linu-c6x-2.0-n55 (bill@gtengapp01) (gcc
version 4.5.1 (Sourcery CodeBench Lite 4.5-124) ) #1 Fri
Sep 30 21:03:10 EDT 2011
Designed for the EVMC6670 board, Texas Instruments.

```

*Revision A:*

---

```
CPU0: C66x rev 0x0, 1.2 volts, 983MHz
Initializing kernel
physical RAM map changed by user
Built 1 zonelists in Zone order, mobility grouping on. Total pages: 65024
Kernel command line: console=ttyS0,115200 rw mem=256M ip=dhcp
initrd=0x80400000,0x400000
PID hash table entries: 1024 (order: 0, 4096 bytes)
Dentry cache hash table entries: 32768 (order: 5, 131072 bytes)
Inode-cache hash table entries: 16384 (order: 4, 65536 bytes)
Memory available: 251828k/258184k RAM, 0k/0k ROM (785k kernel code, 202k data)
SLUB: Genslabs=7, HWalign=128, Order=0-3, MinObjects=0, CPUs=1, Nodes=1
Hierarchical RCU implementation.
RCU-based detection of stalled CPUs is enabled.
NR_IRQS:328
Console: colour dummy device 80x25
Calibrating delay loop... 980.99 BogoMIPS (lpj=1961984)
Mount-cache hash table entries: 512
C64x: 13 gpio irqs
NET: Registered protocol family 16
SGMII init complete
bio: create slab <bio-0> at 0
Switching to clocksource TSC64
NET: Registered protocol family 2
IP route cache hash table entries: 2048 (order: 1, 8192 bytes)
TCP established hash table entries: 8192 (order: 4, 65536 bytes)
TCP bind hash table entries: 8192 (order: 3, 32768 bytes)
TCP: Hash tables configured (established 8192 bind 8192)
TCP reno registered
UDP hash table entries: 256 (order: 0, 4096 bytes)
UDP-Lite hash table entries: 256 (order: 0, 4096 bytes)
NET: Registered protocol family 1
RPC: Registered udp transport module.
RPC: Registered tcp transport module.
RPC: Registered tcp NFSv4.1 backchannel transport module.
Trying to unpack rootfs image as initramfs...
Freeing initrd memory: 4096k freed
JFFS2 version 2.2. (NAND) (SUMMARY)  © 2001-2006 Red Hat, Inc.
ROMFS MTD (C) 2007 Red Hat, Inc.
msgmni has been set to 499
Block layer SCSI generic (bsg) driver version 0.4 loaded (major 254)
io scheduler noop registered
io scheduler deadline registered
io scheduler cfq registered (default)
Serial: 8250/16550 driver, 1 ports, IRQ sharing disabled
serial18250.0: ttyS0 at MMIO 0x2540000 (irq = 292) is a 16550A
console [ttyS0] enabled
brd: module loaded
loop: module loaded
at24 1-0050: 131072 byte 24c1024 EEPROM (writable)
uclinux[mtd]: RAM probe address=0x803dd7c0 size=0x0
Creating 1 MTD partitions on "RAM":
0x000000000000-0x000000000000 : "ROMfs"
mtd: partition "ROMfs" is out of reach -- disabled
Generic platform RAM MTD, (c) 2004 Simtec Electronics
GPIO NAND driver for C6x SoC boards
NAND device: Manufacturer ID: 0x20, Chip ID: 0x36 (ST Micro NAND 64MiB 1,8V 8-bit)
Scanning device for bad blocks
```

```

RedBoot partition parsing not available
Using static partition definition
Creating 3 MTD partitions on "gpio-nand-c6x":
0x000000000000-0x00000004000 : "bootconfig"
0x00000004000-0x00001000000 : "kernel"
0x00001000000-0x00004000000 : "filesystem"
keystone_netcp keystone_netcp.0: firmware: using built-in firmware
keystone-pdsp/qmss_pdsp_acc48_le.fw
keystone_netcp keystone_netcp.0: firmware: using built-in firmware
keystone-pdsp/pa_pdsp_default.fw
pktgen 2.72: Packet Generator for packet performance testing.
TCP cubic registered
NET: Registered protocol family 17
Sending DHCP requests ., OK
IP-Config: Got DHCP answer from 0.0.0.0, my address is 158.218.103.164
IP-Config: Complete:
    device=eth0, addr=158.218.103.164, mask=255.255.254.0, gw=158.218.102.2,
    host=158.218.103.164, domain=am.dhcp.ti.com, nis-domain=(none),
    bootserver=0.0.0.0, rootserver=0.0.0.0, rootpath=
Freeing unused kernel memory: 136K freed
starting pid 18, tty '' '/etc/rc.sysinit'

Starting system...

Mounting proc filesystem: done.
Mounting other filesystems: done.
Starting mdev
Setting hostname 158.218.103.164: done.
Bringing up loopback interface: done.
Starting inetd: done.

eth0      Link encap:Ethernet HWaddr 90:D7:EB:9E:5F:83
          inet addr:158.218.103.164 Bcast:158.218.103.255 Mask:255.255.254.0
          UP BROADCAST RUNNING MULTICAST MTU:1500 Metric:1
          RX packets:12 errors:0 dropped:0 overruns:0 frame:0
          TX packets:2 errors:0 dropped:0 overruns:0 carrier:0
          collisions:0 txqueuelen:1000
          RX bytes:2653 (2.5 KiB) TX bytes:1180 (1.1 KiB)
          Interrupt:48

System started.

starting pid 67, tty '/dev/console': '/bin/sh'
/ #

```

#### 7.9.28.4.2 EVMK2H

**Note: for EVMK2H it is necessary to reformat the NAND Flash prior to burning the image. To do this, use the following command:**

```
%DSS_SCRIPT_DIR%\dss.bat program_evm.js evmk2h format-nand
```

1. Set the dip switches as below.

*Revision A:*

<b>SWITCH</b>	<b>Pin1</b>	<b>Pin2</b>	<b>Pin3</b>	<b>Pin4</b>
SW1	<b>Off</b>	<b>Off</b>	On	<b>Off</b>

2. Power Cycle the board. U-Boot will show up on the UART.

3. Type the following commands into U-Boot:

```
> env default -f -a  
> setenv boot ubi  
> setenv mtdparts 'mtdparts=davinci_nand.0:1024k(bootloader),512k(params)ro,129536k(ubifs)'  
> boot
```

4. A sample screen is shown below.



The screenshot shows a terminal window with a dark background and light-colored text. It displays a boot log from a system named 'Arago'. The log includes messages about starting daemons like thttpd, lighttpd, and vsftpd, and stopping the bootlog daemon. It also shows the Arago Project logo and version information ('Arago 2013.02'). At the bottom, it prompts for a keystroke ('keystone-evm') and shows a login prompt ('keystone-evm login:').

```
source s_src < unix-dparam("//dev/log"); internal();

syslog-ng documentation: http://www.balabit.com/support/documentation/?product=s
syslog-ng mailing list: https://lists.balabit.hu/mailman/listinfo/syslog-ng

Starting thttpd.
Starting Lighttpd Web Server: 2013-03-29 00:15:03: <log.c.166> server started
lighttpd.
* starting FTP Server: vsftpd... done.
Stopping Bootlog daemon: bootlogd.

[REDACTED] Arago [REDACTED] Arago [REDACTED] Arago [REDACTED]

Arago Project http://arago-project.org keystone-evm ttyS0
Arago 2013.02 keystone-evm ttyS0
keystone-evm login:
```